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T7-062: Performance Sensitivities for Parameterized Systems

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T2-025: A Teleoperating System for Underwater Manipulator to Practice a Time Limit Task

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T1-011: Decentralized Variable Structure Control for Interconnected Systems with Mismatched Uncertainties

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T3-021: A New Application of Fuzzy Neural Network to ECG Recognition Based on Rough Set Theory

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T7-084: Stability Analysis of Low-Order Combustion Systems

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T7-068: Application of Lifting Scheme to Transmultiplexers

Zoppi, M.

IV06-01: Mechatronic Design of a Parallel Robot for High-Speed, Impedance-Controlled Manipulation

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T2-021: Robot Force Control: Some Comments on System Convergence

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