

On Readily Available Supervisory Control Policies that Enforce Liveness in a Class of Completely Controlled Petri Nets

Ramavarapu S. Sreenivas*
Coordinated Science Laboratory
and
Department of General Engineering
University of Illinois at Urbana-Champaign
Urbana, IL 61801
E-mail: rsree@uiuc.edu

Keywords: DEDS, Supervisory Control, Petri nets, Liveness

April 12, 1999

Abstract

A *Petri Net* (PN) is said to be *live* if it is possible to fire any transition from every reachable marking, although not necessarily immediately. Under appropriate conditions, a non-live PN can be made live via supervision. Under this paradigm an external-agent, the supervisor, prevents the firing of certain transitions at each reachable marking so as to enforce liveness. A PN is said to be completely controllable if the supervisor can prevent the firing of any transition. Testing the existence of a supervisory policy that enforces *liveness* in a completely controlled Petri net can be computationally expensive [8]. In this paper we present a new class of PNs for which there is a readily available supervisory policy that enforces liveness. This observation obviates the aforementioned test for the specific class of PNs introduced in this paper.

1 Introduction

A *Petri net* (PN) [3, 5, 4] is said to be *live* if it is possible to fire any transition from every reachable marking, although not necessarily immediately. In this paper we concern ourselves with the problem of enforcing liveness in a non-live PN via supervision. Essentially, we have a non-live PN where some, maybe all, transitions can be individually prevented from firing by an external-agent, the supervisor. A PN where every transition can (cannot) be individually prevented from firing by the supervisor is called a *completely controlled PN* (*partially controllable PN*). In reference [8] it is shown that the existence of a supervisory policy that enforces liveness in a partially controllable PN is undecidable in general. However, in the same reference it

*This work was supported in part by the National Science Foundation under grant numbers ECS-9812591 and ECS-9807106.

is shown that there exists a testable condition for the existence of a supervisory policy that enforces liveness in an arbitrary completely controllable PN. Additionally, the computational requirements for this test are exponential in the number of places.

In deciding the existence and the synthesis of a supervisory policy that enforces liveness, significant savings in computation can be gained if the PN satisfies specific structural requirements [10, 11]. Different approaches to circumventing the aforementioned complexity issues in references [6] is shown that there is a supervisory policy that enforces liveness in a completely controlled PN if and only if there is a corresponding policy for its *E-Choice Equivalent*. A *F-re-Choice PN* (FCPN) is a PN where every arc from a place to a transition is either the unique output arc from that place or the unique input arc to that transition. Supervisory policies that enforce liveness in FCPNs are characterized in reference [7].

In this paper, we present a new class of PN for which there is a readily available policy that enforces liveness. This observation eliminates the computationally expensive search for the existence of a supervisory policy that enforces liveness when a plan $t \in P \setminus N$ is known to belong to this class of PN.

The next section contains notations and definitions of the various concepts used in this paper. We present the main results of this paper along with an illustrative example. The concluding section presents a potential future research topic.

Notation and Definitions

A *Petri net* (PN) $N = (\Pi, T, \Phi, m^0)$ is an ordered 4-tuple where $\Pi = \{p_1, p_2, \dots, p_n\}$ is a set of n places, $T = \{t_1, t_2, \dots, t_m\}$ is a set of m transitions, $\Phi \subseteq (\Pi \times T) \cup (T \times \Pi)$ is a set of arcs, $m^0: \Pi \rightarrow \mathcal{N}$ is the *initial marking function* (or the *initial marking*) and \mathcal{N} is a set of nonnegative integers. The *state* of a PN is a marking $m: \Pi \rightarrow \mathcal{N}$ that identifies the number of tokens in each place. A marking m at a transition $t \in T$ is said to be *enabled* if $\forall p \in (\bullet t)_N, m(p) \geq 1$ where $(\bullet x)_N := \{y \mid (y, x) \in \Phi\}$. The set of enabled transitions is denoted by $T_e(m)$. An enabled transition $t \in T_e(m)$ can fire which changes the marking m to \widehat{m} according to the equation

$$\widehat{m}(p) = m(p) \Leftrightarrow \text{card}((p \bullet)_N \cap \{t\}) + \text{card}((\bullet p)_N \cap \{t\}), \quad (1)$$

where $(x \bullet)_N := \{y \mid (x, y) \in \Phi\}$ and $\text{card}(\bullet)$ is used to denote the cardinality of the set. The notation pre is also used to denote the predecessor set and post to denote the successor set.

of places and transitions. Sometimes $(x^\bullet)_N$ (or $(\bullet x)_N$) is just represented as x^\bullet ($\bullet x$) when there is no confusion as to the definition of P .

A collection of places $P \subseteq \Pi$ is said to be a *siphon* if $P \subseteq P^\bullet$ ($P^\bullet \subseteq P$). A siphon P is said to be *minimal* if $\nexists \tilde{P} \subset P$ such that $\tilde{P}^\bullet \subseteq \bullet \tilde{P}$ ($\bullet \tilde{P} \subseteq \tilde{P}^\bullet$).

A string of transitions $\sigma = t_{j_1} t_{j_2} \cdots t_{j_k}$ where $t_{j_i} \in T$ ($i \in \{1, 2, \dots, k\}$) is said to be a *valid firing string* starting from the marking m if,

- the transition t_{j_i} is enabled at the marking m and
- for $i \in \{1, 2, \dots, k-1\}$ the firing of the transition t_{j_i} produces a marking m' where the transition $t_{j_{i+1}}$ is enabled.

The set of *reachable markings* from m^0 denoted by $\mathcal{R}(N, m^0)$ is the set of markings generated by all firing strings starting with marking m^0 in the PN N . A marking m^1 is the firing of a firing string σ results in marking m^2 , we represent it as $m^1 \rightarrow \sigma \rightarrow m^2$. A transition $t \in T$ is *live* if

$$\forall m^1 \in \mathcal{R}(N, m^0), \exists a m^2 \in \mathcal{R}(N, m^1) \text{ such that } t \in T_e(m^2).$$

A *supervisory policy* $\mathcal{P}: \mathcal{N}^n \rightarrow \{0, 1\}^m$ is a total map that returns an m -dimensional binary vector for each reachable marking. The supervisory policy \mathcal{P} permits the firing of transition t_i at a marking m only if $\mathcal{P}(m)_i = 1$. If a marking m in all input places of a transition t_i contains $\mathcal{P}(m)_i$ tokens, the transition t_i is *state-enabled* at m . If $\mathcal{P}(m)_i = 1$, the transition t_i is *control-enabled* at m . A transition is *state-enabled* and *control-enabled* before a firing string of transitions $\sigma = t_{j_1} t_{j_2} \cdots t_{j_k}$ where $t_{j_i} \in T$ ($i \in \{1, 2, \dots, k\}$) is said to be a *valid firing string* starting from the marking m if,

- the transition t_{j_i} is enabled at the marking m , $\mathcal{P}(m)_{j_i} = 1$ and
- for $i \in \{1, 2, \dots, k-1\}$ the firing of the transition t_{j_i} produces a marking \tilde{m} at which the transition $t_{j_{i+1}}$ is enabled and $\mathcal{P}(\tilde{m})_{j_{i+1}} = 1$.

The set of *reachable markings* under the supervision of \mathcal{P} in N from the initial marking m^0 is denoted by $\mathcal{R}(N, m^0, \mathcal{P})$. A transition t_{j_i} is *live* under the supervision of \mathcal{P} if

$$\forall m^1 \in \mathcal{R}(N, m^0, \mathcal{P}), \exists m^2 \in \mathcal{R}(N, m^1, \mathcal{P}) \text{ such that } t_{j_i} \in T_e(m^2) \text{ and } \mathcal{P}(m^2)_{j_i} = 1.$$

A supervisory policy \mathcal{P} enforces liveness if all transitions in N are live under \mathcal{P} . A supervisory policy \mathcal{P} that enforces liveness in N essentially eliminates those markings reachable under the

absence of supervision from which some transition in the PN is enabled. The above definition of supervisory policy that enforces liveness in completely controlled PNs is simpler than that in reference [8] which addresses the general case when some transitions in the PN cannot be fired from rings. The supervisory Reference [8] presents a necessary and sufficient condition for the existence of supervisory policy that enforces liveness in arbitrary PN. This condition is not stable in general but is stable if the PN is bounded or if a transition in the PN can be fired from rings. The supervisory policy for completely controlled PN is a supervisory policy that enforces liveness if and only if $\exists m^1, m^2 \in \mathcal{R}(N, m^0), \exists \sigma_1, \sigma_2 \in T^*$ such that $m^0 \rightarrow \sigma_1 \rightarrow m^1 \rightarrow \sigma_2 \rightarrow m^2$ where $m^2 \geq m^1$ and all transition in T appear at least once in σ_2 . The class PN considered in this paper are not necessarily bounded but assume a transition can be fired from rings. The supervisory policy that enforces liveness in an arbitrary bounded PN is at least PSE-complete. In this paper we present a class of PN for which there is readily available supervisory policy that enforces liveness. This class of PN is a subset of class PN called *E-Choice* PN which is defined below.

A PN (N, Π, T, Φ, m^0) is a *Free-Choice* PN (FCPN) if

$$\forall p \in \Pi, \text{card}(p^\bullet) > 1 \Rightarrow (p^\bullet) = \{p\}.$$

In the words of PN Free-Choice and only if a marking of a transition is either the unique output or the unique input of the transition. A FCPN N is *liveness* if and only if for any minimal siphon of N contains at least one place. *Commoner's Liveness Theorem* [1] Reference [7] characterizes the class of policies that enforces liveness in FCPN that violate Commoner's Liveness Theorem. This characterization is presented in theorem 2.1.

Theorem 2.1 [7] *Supervisory policy* $\mathcal{P}: \mathcal{N}^n \rightarrow \{0, 1\}^m$ enforces liveness in FCPN (N, Π, T, Φ, m^0) if and only if the following conditions are satisfied

1. If the supervisory policy \mathcal{P} prevents firing of a state-enabled transition $t \in T$ at some marking $m \in \mathcal{R}(N, m^0, \mathcal{P})$ then $\exists \hat{m} \in \mathcal{R}(N, \hat{m}^0, \mathcal{P})$ such that the transition t is both state and ctrl-enabled at the marking \hat{m} .

2. $\forall m \in \mathcal{R}(N, m^0, \mathcal{P}), \forall P \subseteq \Pi$ such that ${}^\bullet P \subseteq P^\bullet, \sum_{p \in P} m(p) \neq 0$.

An arbitrary PN (N, Π, T, Φ, m^0) is a bounded and equivalent to FCPN $\tilde{N} = (\tilde{\Pi}, \tilde{T}, \tilde{\Phi}, \tilde{m}^0)$ with the addition of few extra places and transitions (cf. [16]). Additionally, in

```

(PN) Compute_Subnet ((PN) N = (Π, T, Φ, m0), Subsetsplaces Π1 ⊆ Π, Subsetsitions T1 ⊆ T)
{
    Createplaces Π̂ = Π1;
    Createfransitions T̂ = T1;
    while( (•T̂)N ≠ Π̂) do {
        Π̂ = Π̂ ∪ (•T̂)N;
        T̂ = T̂ ∪ (•Π̂)N;
    }
    Construct/drawarcsthet Φ̂ where Φ̂ = {(Π̂ × T̂) ∪ (T̂ × Π̂)} ∩ Φ;
    Defineñinitial-marking m̂0 as follows: ∀p ∈ Π̂, m̂0(p) = m0(p);
return( N̂ = (Π̂, T̂, Φ̂, m̂0));
}

FigureTheprocedure N̂ = Compute_Subnet(N, Π1, T1) where N̂ = (Π̂, T̂, Φ̂, m̂0).

```

reference [6] shows that there exists supervisor policy that enforces liveness in the PN

N if and only if there exists a corresponding policy for the CPN \tilde{N} . The following result establishes the fact that there is supervisor policy that enforces liveness in the PN N if and only if there is a corresponding policy for the CPN \tilde{N} .

Theorem 2.2 [6] Let $\tilde{N} = (\tilde{\Pi}, \tilde{T}, \tilde{\Phi}, \tilde{m}^0)$ be a free-choice Petri net equivalent to PN $N = (\Pi, T, \Phi, m^0)$. Then there exists supervisor policy that enforces liveness in the PN N if and only if there exists a corresponding policy for the CPN \tilde{N} .

Given an arbitrary PN $N = (\Pi, T, \Phi, m^0)$ and a subset of places $\Pi_1 \subseteq \Pi$ and transitions $T_1 \subseteq T$, we define a subnet $\hat{N}(\Pi_1, T_1) = (\hat{\Pi}, \hat{T}, \hat{\Phi}, \hat{m}^0)$ of the PN N as described in the procedure outlined in Figure 1. The PN \hat{N} is the subnet induced by the transition closure of the input places and input transitions to T_1 and Π_1 . Since the sets T and Π are finite sets, the while-loop in the procedure of Figure 1 is guaranteed to halt. We present the main results of this paper.

Main Results

Let $N = (\Pi, T, \Phi, m^0)$ be an arbitrary PN and let $\tilde{N} = (\tilde{\Pi}, \tilde{T}, \tilde{\Phi}, \tilde{m}^0)$ be a free-choice equivalent PN. Theorem 3.1 implies there is supervisor policy that enforces liveness in N only if there is a minimal siphon $\bullet P \subseteq P^* (P \subseteq \tilde{\Pi})$ that does not contain a trap is not empty at the initial

marking and here an input transition \hat{t} to some place in P (i.e. $\hat{t} \in \bullet P$) has more than one output place in P (i.e. $\text{card}(\hat{t}^\bullet \cap P) > 1$).

Theorem 3.1 *Let $N = (\Pi, T, \Phi, m^0)$ be an arbitrary PN and let $\tilde{N} = (\tilde{\Pi}, \tilde{T}, \tilde{\Phi}, \tilde{m}^0)$ be a E-Choice equivalent PN. Then there exists a supervisor policy that enforces liveness in N only if:*

1. $\sum_{p \in P} m^0(p) > 0$ and
2. $\exists \hat{t} \in \bullet P$ such that $\text{card}(\hat{t}^\bullet \cap P) > 1$.

Proof: For theorem 2.2, there is a supervisor policy that enforces liveness in the

completely controlled PN N if and only if there is a corresponding policy for the E-Choice equivalent \tilde{N} . To complete the proof using a traposition argument, we show that the conditions of the theorem are necessary for the existence of a policy that enforces liveness in \tilde{N} .

Since $\bullet P \subseteq P^\bullet$, if $\sum_{p \in P} m^0(p) = 0$, then under any supervisor policy \mathcal{P} it follows that $\forall m^1 \in \mathcal{R}(N, m^0, \mathcal{P})$, $\sum_{p \in P} m^1(p) = 0$. It then implies one of the transitions in P^\bullet cannot be used for the supervision of P .

First, note that if P is minimal, $\text{card}(\bullet \hat{t} \cap P) = 1, \forall \hat{t} \in \bullet P$ (cf observation 1).

If $\text{card}(\hat{t}^\bullet \cap P) = 1, \forall \hat{t} \in \bullet P$, then the sum of the loads of the places in P will remain unaltered following the firing of a transition $\tilde{t} \in \bullet P$. That is, $\sum_{p \in P} m^1(p) = \sum_{p \in P} m^2(p)$ where $m^1 \rightarrow \tilde{t} \rightarrow m^2$ and $\tilde{t} \in \bullet P$. However, since \tilde{N} is a PN, this sum will decrease unit by unit at every time a transition in $P^\bullet \Leftrightarrow P$ fires. It follows that under any supervisor policy \mathcal{P} the transition in $P^\bullet \Leftrightarrow P$ can fire only a finite number of times. Consequently, there can be no policy that enforces liveness in \tilde{N} . Hence the second observation. ♣

The conditions of theorem 3.1 are not sufficient in general. The PN shown in figure 8 is a EPN. So, $\tilde{N} = N$ and \tilde{N} has minimal siphons $P_1 (= \{p_1, p_3, p_4, p_7, p_9\})$ and $P_2 (= \{p_2, p_5, p_6, p_8, p_9\})$ that do not contain traps. Additionally, $t_1 \in \bullet P_1, t_2 \in \bullet P_2, \text{card}(t_1^\bullet \cap P_1) > 1, \text{card}(t_2^\bullet \cap P_2) > 1$ and both minimal siphons are non-empty. The initial marking from reference [8] does not have a supervisor policy that enforces liveness in this EPN and only if $\exists m^1, m^2 \in \mathcal{R}(N, m^0), \exists \sigma_1, \sigma_2 \in T^*$ such that $m^0 \rightarrow \sigma_1 \rightarrow m^1 \rightarrow \sigma_2 \rightarrow m^2, m^2 \geq m^1$

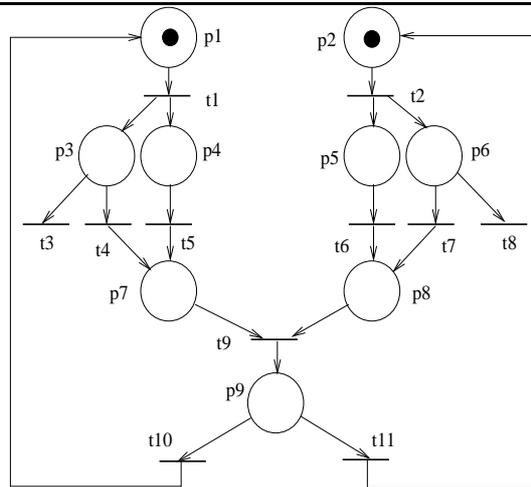


Figure 2. An illustration of the sufficiency of the conditions of theorem 3 for the existence of a supervisory policy that enforces liveness.

and all transitions in T appear at least once in σ_2 . Since, $m^2 = m^1 + Cx(\sigma_2)$ if $m^2 \geq m^1$ it follows that $Cx(\sigma_2) \geq 0$. For the EPN shown in figure 2, there does not exist a $\sigma_2 \in T^*$ with the required properties, therefore there can be no supervisory policy that enforces liveness, although the conditions of theorem 3 are satisfied. The fact that there is no string σ_2 with the desired properties can be inferred from this Lemma: $\exists x > 0$ such that $Cx \geq 0 \Leftrightarrow \exists y \geq 0$ such that $y^T C \leq 0$ and some element of $y^T C$ is strictly less than zero. For the incidence matrix C of the EPN N , we note that $y^T C = (0 \ 0 \ -1 \ 0 \ 0 \ 0 \ 0 \ -1 \ 0 \ 0)^T = (f_2 \ 2 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 2)$. We note that there are nine classes of EPNs, consequently, classes of EPNs whose F-Choice equivalent belong to this class of EPNs where the conditions of theorem 3 are also sufficient for the existence of a supervisory policy that enforces liveness. We suggest the identification of this class as a future research topic. We state the main result of this paper.

Theorem 3.2 Let $N = (\Pi, T, \Phi, m^0)$ be an arbitrary EPN and let $\tilde{N} = (\tilde{\Pi}, \tilde{T}, \tilde{\Phi}, \tilde{m}^0)$ be its F-Choice equivalent. Then there exists a supervisory policy that enforces liveness in N if and only if there exists a place $P \subseteq \tilde{\Pi}$ in \tilde{N} that contains a marked place and satisfies the following properties:

1. $\exists \hat{t} \in \bullet P$ such that $card(\hat{t} \cap P) > 1$ (cf. theorem 3.1),
2. The EPN $\hat{N} = Compute_Subnet(\tilde{N}, (\bullet \hat{t})_{\tilde{N}}, \{\hat{t}\})$ is live,

The place $\bullet \hat{t} \cap P$ is bounded in \hat{N} and
 4. $\hat{\Pi} \bullet \Leftrightarrow (P \bullet \cup \hat{T}) = \emptyset$ where $\hat{N} = (\hat{\Pi}, \hat{T}, \hat{\Phi}, \hat{m}^0)$.

Proof: Consider a transition $t \in P \bullet \Leftrightarrow \hat{T}$ where $P \subseteq \tilde{\Pi}$ is some minimaliphon of \tilde{N} that does not contain a trap. Using theorem 2.1 we have a supervisory policy that permits the firing of the transition t only if

- the marking resulting from the firing of t in \tilde{N} keeps the subnet of \tilde{N} that is identical to $\hat{N}(\bullet \hat{t}, \{\hat{t}\})$ bounded
- the place $p = (\bullet \hat{t})_{\tilde{N}} \cap P$ is bounded in this subnet at the new marking,

enforced in \tilde{N} . A transition that does not fit the description of t is disabled by a permanently control-enabled policy.

Under this supervisory policy the minimaliphons are emptied. This observation can be established by the trap position argument for minimaliphons emptied at

some marking m^i , the subnet of \tilde{N} that is identical to $\hat{N}(\bullet \hat{t}, \{\hat{t}\})$ would obviously be a trap. A marking m^i and a supervisory policy would permit the firing of the transition that resulted in the marking m^i .

If a transition $t \in \tilde{T}$ is prevented from firing under the prescribed supervisory policy at some marking m^i , then one of the conditions in the statement of the policy must

be violated in the marking m^{i+1} arising from the firing of the transition t (i.e. $m^i \rightarrow t \rightarrow m^{i+1}$). It can be shown that there is a marking m^j reachable

from the marking m^i at which the transition t is both control and state-enabled. This observation can be established using conditions 2 and 3 in the statement of the theorem.

As a consequence of theorem 2.1 we infer that the supervisory policy mentioned above enforces liveness. Hence the result. □

Consider the EPN N_1 shown in figure 3(a), the EPNs N_2 and N_3 shown in figure 3(b) and N_4 shown in figure 3(c). $card(p_8^\bullet) = 2$ and $\bullet(p_8^\bullet) = \{p_5, p_6\} (\neq \{p_8\})$. Figure 3(b) contains the free choice equivalent EPN N_2 (cf. [10]).

N_1 shown in figure 3(a) has three minimaliphons, the EPNs shown in figure 3(b):

$P_1 = \{p_5, p_6\}$, $P_2 = \{p_1, p_3, p_4, p_7\}$ and $P_3 = \{p_2, p_3, p_4, p_5, p_7, p_8, p_9\}$. The iphon P_1 is also

trapped and is a dead iphon. The iphons P_2 and P_3 do not contain a trap and therefore the EPN is live in the absence of supervision.

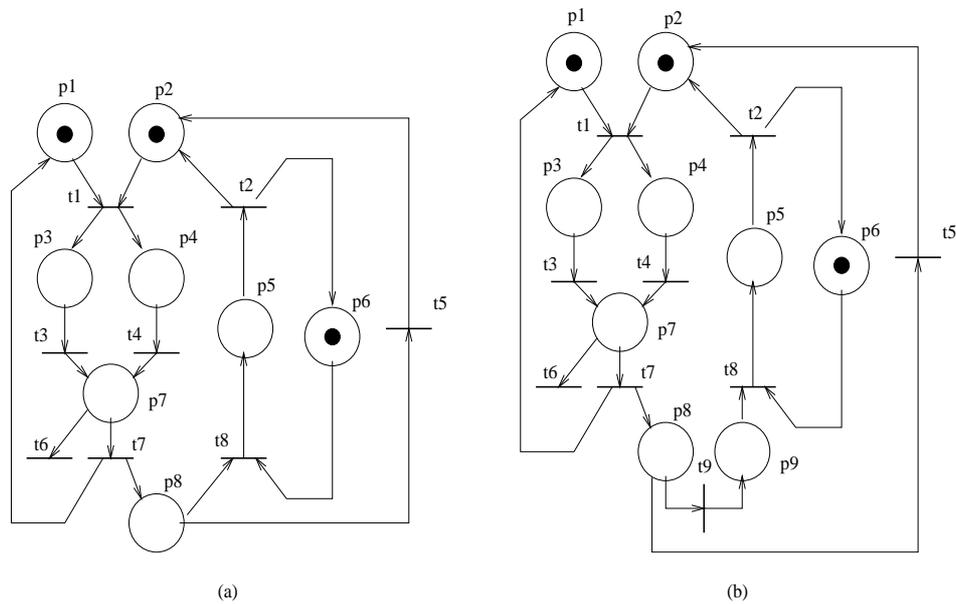


Figure 3: Illustration of theorem 3.2.

Since $t_1^* = \{p_3, p_4\}$ the first requirement of theorem 3.2 is satisfied. The EPN $\hat{N} = \text{Compute_Subnet}(N_2, (\bullet t_1)_{N_2}, \{t_1\})$ is the EPN N_2 without the transition t_1 . The minimal siphons of this EPN are identical to that of N_2 but with the absence of the transition t_1 . The siphon P_2 contains no traps $\{p_1, p_3, p_7\}$ and $\{p_1, p_4, p_7\}$. Similarly without the transition t_6 , the siphon P_3 contains no traps $\{p_2, p_3, p_5, p_7, p_8, p_9\}$ and $\{p_2, p_4, p_5, p_7, p_8, p_9\}$. By Commoner's Liveness Theorem in the EPN \hat{N} is a live EPN. Additionally for P_1 (P_2) the place p_1 (p_2) is unbounded. \hat{N} satisfies second and third requirements in the statement of theorem 3.2. It is easy to verify the final condition of theorem 3.2. So from theorem 3.2 we know the EPN N_2 can be made live via supervision and from theorem 2.2 in the EPN N_1 can also be made live via supervision. It is hard to see that the supervisory policy that permits the firing of t_6 when the sum of tokens in the place-set $\{p_1, p_3, p_4, p_7\}$ exceeds unity enforces liveness in N_1 and N_2 . The EPN shown in figure 4 for which there is a supervisory policy that enforces liveness does not satisfy the third requirement of theorem 3.2. We suggest investigations to specific EPN structures for which the conditions of theorem 3.2 are also necessary as future research topic. In the following section we conclude with some additional future research directions.

Conclusions

Testing the existence of supervisory policy that enforces liveness in an arbitrary completely controllable Petri net (PN) is computationally expensive. In this paper we identify a class of PN for which a supervisory policy that enforces liveness has been eliminated. This eliminates the need to test the existence of supervisory policy that enforces liveness for this class of PN, what remains is the synthesis of policy that enforces liveness for these PN. We suggest this synthesis as a future research topic. We surmise that the policy that enforces liveness in the free choice equivalent of the PN which is outlined in the proof of theorem 3.2 of this paper, can be modified to enforce liveness in the original PN.

References

- [1] M.H.T.Haas. Analysis of production line material Petri nets Master's thesis Massachusetts Institute of Technology, February 1972.
- [2] M.H.T.Haas. Extended state-machine allocatable nets (ESMA) A extension of free choice Petri net results. Technical Report CSGM-78-1 Project MAC Massachusetts Institute of Technology June 1974.
- [3] Murata. Petri nets properties analysis and applications. *Proceedings of IEEE* 77(4):541-580 April 1989.
- [4] J.Peterson. *Petri nets theory and modeling systems*. Prentice-Hall Englewood Cliffs NJ 1981.
- [5] W.Reisig. *Petri Nets* Springer-Verlag Berlin 1985.
- [6] R.S.Sreenivas. On free choice equivalent Petri net. In *Proceedings of the 26th IEEE Conference on Decision and Control* December 1997 San Diego CA.
- [7] R.S.Sreenivas. A Commoner's Liveness Theorem and supervisory policies that enforce liveness in Free choice Petri nets. *Systems & Control Letters* 31:41-48 1997.
- [8] R.S.Sreenivas. On the existence of supervisory policies that enforce liveness in discrete time dynamical systems modeled by controlled Petri nets. *IEEE Transactions on Automatic Control*, 42(7) July 1997.

- [9] R. Sreenivas. An application of independent increasing reachability to the synthesis of policies that enforce liveness in arbitrary petri nets. *Automatica* 34(12):1613–1615 December 1998.
- [10] R. Sreenivas. On supervisory policies that enforce liveness in a class of completely controlled petri nets obtained via refinement. *IEEE Transactions on Automatic Control* 44(1):173–177 January 1999.
- [11] R. Sreenivas. On supervisory policies that enforce liveness in completely controlled petri nets with directed cut-places and cut-transitions. *IEEE Transactions on Automatic Control* , 1999. To appear Circa 1999-2000.